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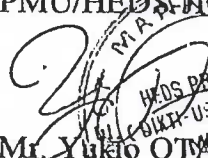
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Adalah benar telah melakukan presentasi makalahnya yang berjudul "Joint Optimization Of Data Network Design and Faculty Selection by Using Linear Programming Method" di University of Malaya, Malaysia pada tanggal 27 Maret 1997 dalam rangka Technical Exchange Program di Malaysia (25 s.d 30 Maret 1997).

Demikian surat keterangan ini diberikan kepada yang bersangkutan untuk digunakan sebagaimana mestinya.

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**JOINT OPTIMIZATION OF DATA NETWORK DESIGN AND FACILITY SELECTION  
BY USING LINEAR PROGRAMMING METHOD**

by

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# **JOINT OPTIMIZATION OF DATA NETWORK DESIGN AND FACILITY SELECTION BY USING LINEAR PROGRAMMING METHOD**

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## **ABSTRACT**

The goal of optimal network design and facility engineering is to arrive at network topologies that minimize total network cost while selecting facility types, allocating capacity, and routing traffic to accommodate demand and performance requirements. This research describes a data network design model based on a Mixed Integer/Linear Programming (MILP) formulation, as do most other approaches, separate link capacity and facility selection from routing and topological design, it fully integrates these processes to capture the very important couplings that exist between them.

We show that our formulation leads to a natural decomposition of the optimal design problem into two subproblems solvable sequentially. We present a link reduction algorithm that efficiently design single or multifacility networks. This algorithm is based on a special-purpose monotonic greedy drop heuristic procedure.

## **INTRODUCTION**

The goal of optimal network design and facility engineering is to generate network topologies that minimize total network cost while selecting facility types, allocating capacity, and routing traffic to accommodate demand and performance requirements. Performance constraint, like average network delay for data networks or end-to-end blocking probabilities for circuit-switched networks and link/node cost function, introduce nonlinearities into optimum design models.

Due to the complexity of the optimal network design problem, Gerla and Kleinrock originally decomposed it into three nonlinear subproblem: optimal capacity assignment, optimal routing, and optimal topological design; however these problem are coupled. We extend the scope of the problem by including transmission facility selection into the model.

Our research describes an Mixed Integer/Linear Programming ( MILP ) model data network design that does not rely on direct decomposition of the problem, but integrates routing, capacity assignment, facility selection and topological design. This MILP problem is naturally decomposed into two subproblems which can be solved sequentially. The first subproblem is MILP-Reduction ( MILP-R) and the second subproblem is optimal capacity assignment.

## **MATHEMATICAL MODEL**

Now formulated our mathematical model for joint optimal topological design, capacity assignment, routing, and facility selection based on tradeoff between cost and performance.

Optimization Problem Formulation

The MILP problem is formulated as:

Minimize

$$\bar{C} = \sum_{t,mn} (A_{mn}^t \eta_{mn}^t + B_{mn}^t \alpha_{mn}^t) + \sum_n o_n \beta_n$$

Subject to

$$0 \leq \beta_n \leq \hat{\beta}_n$$

$$0 \leq \alpha_{mn}^t \leq \hat{\alpha}_{mn}^t \eta_{mn}^t$$

$$f_{mn}^t \leq \rho_L^t \alpha_{mn}^t \text{ and } f_m \leq \rho_N \beta_n$$

$$D^* \leq D_0$$

$$\sum_{n,t} \eta_{mn}^t \geq M$$

given that,

$$\eta_{mn}^t = 1 \quad \text{if facility } t \text{ on link } mn \text{ of the garph } G \text{ is activated}$$

$$= 0 \quad \text{otherwise}$$

The following reduced Mixed Integer-Linear Programming problem (MILP-R) for minimum-cost joint topological design, facility selection, and routing

Minimize,

$$\bar{C} = \sum_{t,mn} (A_{mn}^t \eta_{mn}^t + (B_{mn}^t / \rho_L^t) f_{mn}^t) + \sum_n (O_n / \rho_N) f_n$$

Subject to,

$$f_{mn}^t / \rho_L^t \leq \hat{\alpha}_{mn}^t \eta_{mn}^t$$

$$f_m \leq \hat{\beta}_m \rho_N$$

$$D^* \leq D_0$$

$$\sum_S h_s^k = \lambda^k \text{ dan } h_s^k \geq 0$$

$$\sum_{t,n} \eta_{mn}^t \geq M$$

$$\sum_t \eta_{mn}^t = 0, 1$$

### DISCUSSION

This research describes a data network design model based on a MILP, and solution of this problem utilize the link reduction algorithm. We present a fast link reduction algorithm that efficiently design **Single and Multifacility** network. This algorithm is based on a special-purpose greedy drop heuristic procedure

The routing problem, we develop three standard algorithms for shortest path problem:

**Bellman-Ford, Dijkstra, and Floyd-Warshall** algorithm.

## PROGRESS RESEARCH REPORT

In this paper we report the progress research report, comprise:

A. Link Reduction algorithm for Single Facility as follows:

We define a topology  $T^V$  and its associated cost  $C^V$  at iteration  $v$  of the algorithm. A new topology  $T_{mn}^V$  with cost  $C_{mn}^V$  is constructed by deleting candidate link  $mn$ . For each candidate link  $mn$  pre-eliminated, we evaluate a  $\Delta C_{mn}^V$  to reflect the cost differential of this pre-elimination. We denote by  $\Delta C^V$  the set  $\{ \Delta C_{mn}^V \}$  of pre-elimination candidates. At each iteration  $v$ , the elimination step basically reduces the network of the pre-elimination candidate with maximum  $\Delta C_{mn}^V$ . It generates topologies, verifies a set of constraint, and perform cost comparisons as follows:

Step 0. Initialize  $T^0$  with starting graph  $G$ ,  $B_{mn}/\rho_L$  **dan**  $O_n/\rho_N$  **incremental cost metric**,  $C^0$ ,  $h_s^{k0}$ , iteration  $v = 1$ .

Step 1. Pre-elimination of link  $mn$ : generates topology  $T_{mn}^v$  by eliminating a new link  $mn$  in  $T^V$ .

Step 2. Evaluate  $T_{mn}^v$  with respect to reliability and connectivity constrains: if not met go to Step 1.

Else include  $T_{mn}^v$  in  $T^V$ , the set of retained topologies for iteration  $v$

Step 3. Shortest path routing for  $T_{mn}^v$ , compute  $\Delta C_{mn}^v = C^v - C_{mn}^v \rightarrow \Delta C^v$ , if every feasible link  $mn$  reduced then go to Step 4. else go to Step 1.

Step 4. Link elimination procedure:

get cost set  $DC^V$  for topologies in  $\{T^V\}$ , find  $\max_{kl} \Delta C_{kl}^v \rightarrow (\Delta C_{mn}^v, T_{mn}^v)$ ; if  $C^v < C^{v-1}$  or  $(C^v \geq C^{v-1}$  and  $\sum_{mn} \eta_{mn} \geq [(\sum_k \lambda^k) D_0 - N\rho_N/(1 - \rho_N)](1 - \rho_L)/\rho_L)$  then  $T^v = T_{mn}^v$

this defines new reference topology for the next iteration by deleting link  $mn$ ,  $v = v + 1$ ; Go to

Step 1; else stop with solution  $T^{v-1}$

B. Routing Problem

The routing problem, we can only report Bellman-Ford algorithm

Suppose that node 1 is the " destination" node and consider the problem of finding a shortest path from every node to node 1. Assume that there exist at least one path from every node to destination. To simplify the presentation, let us denote  $d_{ij} = \infty$  if  $(i,j)$  is not an arc of the graph

A shortest walk from a given node  $i$  to node 1, subject to the constrain that the walk contains at most  $h$  arcs and goes through node 1 only once, is referred to as a shortest ( $\leq h$ ) walk and its length is denoted by  $d_i^{(h)}$ . By convention, we take

$$D_i^h = 0 \quad \text{for all } h$$

We will prove shortly that  $D_i^h$  can be generated by the iteration

$$D_i^{h+1} = \min_j [d_{ij} + D_j^h] \quad \text{for all } i \neq 1$$

starting from the initial conditions,

$$D_i^0 = \infty \text{ for all } i \neq 1$$

The Bellman-Ford Algorithm, illustrated in Fig. 1

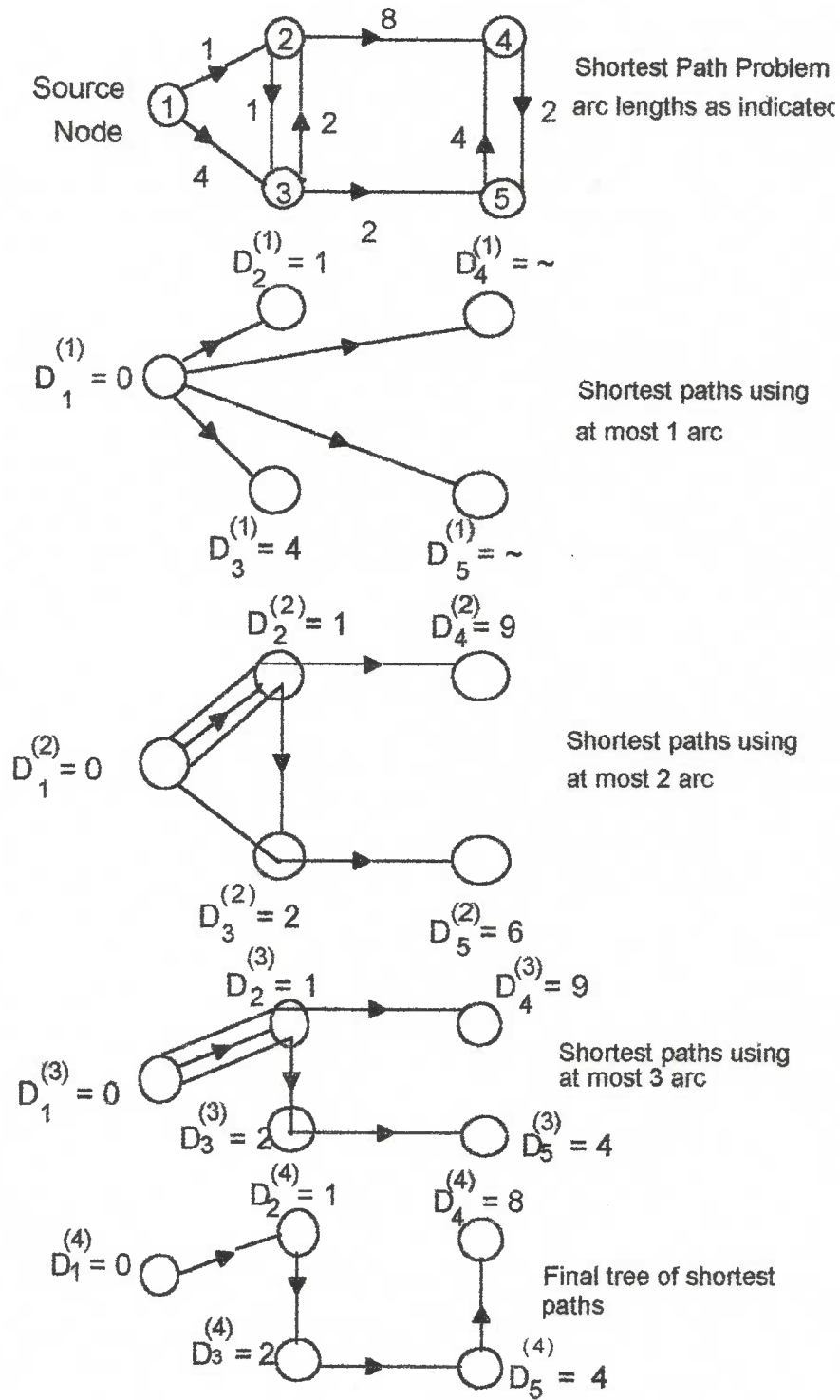


Figure 1 Successive iteration of the Bellman-Ford method

## NEXT PROGRESS OF RESEARCH ACTIVITY

In the next progress of research activity, we report about:

1. Link Reduction algorithm for Multifacility Case
2. Routing problem by Dijkstra and Floyd-Warshall algorithm.

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